

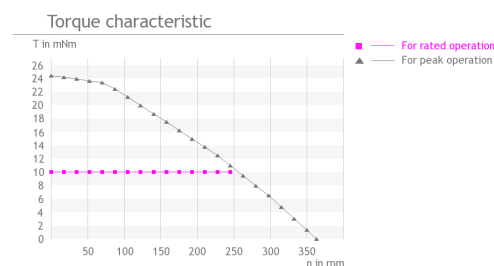


Attributes

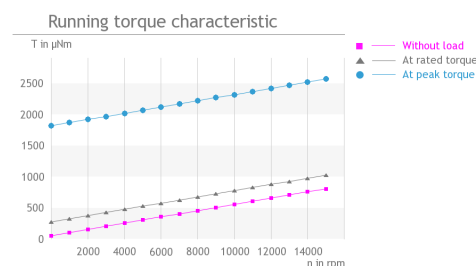
Highlights	Description
<ul style="list-style-type: none"> ▪ High speed ▪ Robust control without feedback system ▪ Preloaded ball bearing ▪ Extreme dynamic ▪ High reliability 	<p>The particularly customer-specific variant of a micro servo actuator is the CoograDrive® MedTec 10mm - type 1. The reliable operating behaviour of this micro positioning system is achieved by the stepper motor with 20 steps per rotation, thereby allowing the unit to be operated in an open loop control in a straightforward manner. At the heart of this micro positioning system is a low-backlash CoograDrive® gear with a reduction ratio of 40:1.</p>

Technical parameter

P-019 Curve measured with 5x nominal voltage and load inertia $6 \cdot 10E-9 \text{ kg/m}^2$ in $\frac{1}{4}$ micro steps.



P-029 Curve measured with 5x nominal voltage and load inertia $6 \cdot 10E-9 \text{ kg/m}^2$ in $\frac{1}{4}$ micro steps.



Nr.	Parameter	Symbol	Value	Hint
P-003	Ratio	i	40 : 1	
P-004	Self-locking		yes	

Technical Supply Specifications: CoograDrive® MedTec 10mm - Type 1



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Nr.	Parameter	Symbol	Value	Hint
P-008	Repeatability unidirectional		4.8 arcmin	
P-009	Repeatability bidirectional		32.7 arcmin	
P-010	Accuracy		35.4 arcmin	
P-011	Transmission accuracy		70.8 arcmin	
P-012	Resolution		0.45 °	
P-013	Torsional stiffness		2.50 ^{Nm} /rad	
P-014	Lost motion		30 arcmin	
P-015	Backlash		20 arcmin	
P-016	Rated torque	T	10 mNm	
P-017	Peak torque	T	80 mNm	
P-018	Momentary peak torque	T	100 mNm	
P-021	Rated input speed	n	10000 rpm	
P-022	Maximum input speed	n	21000 rpm	
P-023	Rated output speed	n	250 rpm	
P-024	Maximum output speed	n	525 rpm	
P-026	No-load starting torque	T	82.5 µNm	
P-027	No-load running torque	T	55 µNm	
P-028	Rated running torque	T	705 µNm	
P-034	Lifetime for rated operation		1000 h	
P-035	Radial backlash output shaft		0 µm	
P-036	Axial backlash output shaft		0 µm	
P-037	Radial stiffness	c	2.3 N/µm	
P-038	Axial stiffness	c	40 N/µm	
P-039	Max. radial load on output shaft (non-operating, constant load)	F	55 N	
P-040	Max. radial load on output shaft (non-operating, impulsive load)	F	20 N	
P-041	Max. radial load on output shaft (operating, constant load)	F	7 N	
P-042	Max. radial load on output shaft (operating, impulsive load)	F	7 N	
P-043	Max. axial load on output shaft (non-operating, constant load)	F	150 N	
P-044	Max. axial load on output shaft (non-operating, impulsive load)	F	50 N	
P-045	Max. axial load on output shaft (operating, constant load)	F	380 N	

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Nr.	Parameter	Symbol	Value	Hint
P-046	Max. axial load on output shaft (operating, impulsive load)	F	127 N	
P-055	Moment of inertia	I	$938.03 \cdot 10^{-4}$ gcm ²	
P-056	Weight	m	22 g	
P-057	Min. permissible ambient temperature (non-operating)	T	-35 °C	
P-058	Min. permissible ambient temperature (operating)	T	-20 °C	
P-059	Max. permissible ambient temperature (non-operating)	T	130 °C	
P-060	Max. permissible ambient temperature (operating)	T	70 °C	

Additional technical data:

- Output shaft is sealed by teflon washers and epoxy and cable:PVC ribbon with color code

Motor data: Stepper AM 1020-2R-A0.25

Nr.	Parameter	Symbol	Value	Hint
P-100	Motortype		Stepper	
P-102	Maximum speed of motor	n	21000 rpm	
P-103	Resonance frequency of motor	f	140 Hz	
P-105	Holding torque of motor (unpowered)	T	0.2 mNm	
P-109	Rated current of motor	I	250 mA	
P-111	Rated voltage of motor	U	2 V	
P-112	Phase resistance of motor	R	8 ohm	
P-113	Inductance of motor	L	2.4 mH	
P-114	Amplitude BEMF of motor	U	0.6 mV/rpm	
P-115	Full step angle of motor		18 °	
P-116	Angular accuracy of step of motor		±1.8 °	
P-117	Electrical time constant of motor	t	0.32 ms	
P-118	Max. coil temperature of motor	T	130 °C	
P-119	Thermal resistance of motor between coil and housing	R _{th1}	3.9 [°] /W	
P-120	Thermal resistance of motor between housing and air	R _{th2}	53.8 [°] /W	
P-121	Thermal time constant of the coil of the motor	T _{w1}	3200 ms	
P-122	Thermal time constant of the housing of the motor	T _{w2}	200000 ms	
P-123	Insulation voltage of motor	U	200 V	

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Material information

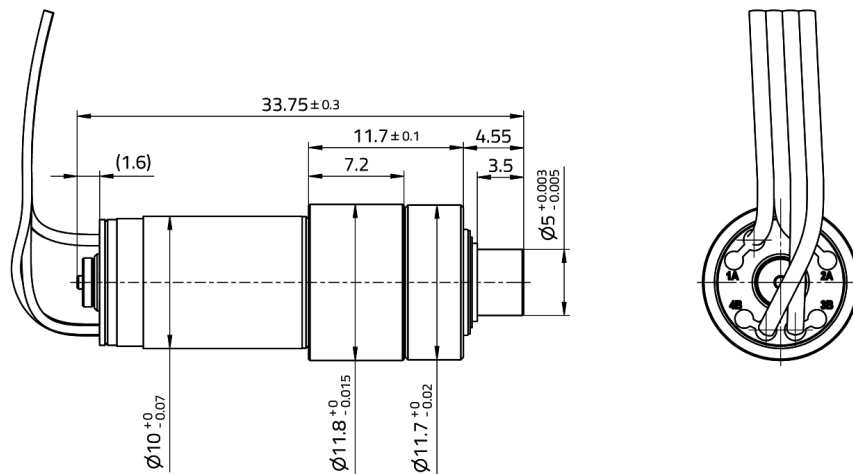
Nr.	Parameter	Symbol	Value	Hint
P-900	RoHS compliant		yes	
P-901	Lubrication of output bearing gearbox		Longtime PD2	
P-903	Lubrication of gear component set		Molykote BR 2 plus	
P-904	Lubrication of bearing motor		Synthetic light ester oil	
P-908	Material of gear component set		NiFe	
P-909	Material of output bearing gearbox		1.4108 DIN EN	
P-911	Material of bearing motor		Stainless steel	
P-912	Material of gearbox output side		1.4305 DIN EN	
P-914	Material of motor housing		Anodized aluminum	

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Technical drawing



cable:
flat ribbon cable, color-coded,
4 leads, AWG28, length=65mm,
ends stripped 7±1mm

Pin assignment	
Color	Signal
BRW	Motor A+
RED	Motor A-
ORA	Motor B+
YEL	Motor B-



Micromotion GmbH | Hoenbergstraße 14 | 65555 Limburg
+49(0)6431-59618-25 | sales@micromotion.de | www.micromotion-drives.com